

Low delta T syndrome



- The difference between supply and return chilled water temperature goes under the design value causing the cooling plant to work less efficiently during more than 90 percent of the years since the full load condition only happens at pick load during summer day time.
- Low delta T syndrome is forcing the plant to consume more energy and building side end users to pay surcharges or penalties.

Reasons of Low delta T syndrome



Main reasons: Design & selection, commissioning, maintenance & operation.

- 1. Design & selection: Oversized or undersized cooling coils & control valves will cause overflows and reduce exchange efficiency resulting in low return temperature.
- 2. Lack of maintenance of the equipment eg. Dirty air filter or coils (outside fins or inside the coil) with reduce the exchange efficiency and cause low return temperature.
- 3. Commissioning: wrong hydronic balancing and pump optimization will result in over pumping during part load causing low return temperature.

.....Example of the above listed below.....

Design & Selection



Common cases: valve size = pipe size

This will cause the valve to have lower pressure drop and reduced authority that will directly affect the flow control range and the valve will work as ON/OFF instead of Modulating.

Cooling coil: oversized cooling coil might lead to bigger tube when modulating and the water velocity will be less than the minimum of 0.3m/s (min 0.3m/s & max 1.5m/s) below 0.3m/s the flow will not be turbulent for proper exchange and lead to reduced return temperature.



Maintenance



Poor maintenance lead to lower exchange and discomfort Dirty air filter lead to inefficient exchange & low return chilled water temperature.

Blocked strainer lead to less flow which will push the controller to open the valve further and cause overflow.



HYDRONIC SYSTEMS - VARIABLE FLOW even more more overflow overflow overflow M Wasted range Flow ۴ even even more more more 0^{1,} overflow overflow overflow 8"0? BIT even even Kν more more more **Control Valve Character** overflow overflow overflow М ۲ **Partner Valves** L D D (Ш **Master Partner Valve**





CONTROL VALVE SIZING CONVENTIONAL

- $Q = Kv V\Delta P$
- $Kv = Q/ \sqrt{\Delta P}$
- Where
- Q : flow rate m³/hr
- ΔP : pressure drop across the control value in bar
- Kv : flow coefficient of the control valve



CONTROL VALVE AUTHORITY

• A calculation done to determine the performance of the control valve's characteristic & capability to control against system pressure.

$$\beta = \frac{\Delta p \text{ open valve}}{\Delta p \text{ open valve} + \Delta p \text{ system}} (x \ 100\%)$$





Excellent	Good	Moderate	Poor	Unacceptable
1-0.76	0.75 – 0.51	0.5 – 0.26	0.25 – 0.11	0.1 - 0



Pipe pressure drop





مجلس الأمار ات للأبنية الخضر اء Emirates Green Building Council

Control Valve Selection



Mechanical DP Controllers: Diffirential Pressure Control Valve (DPCV)









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Flow

Automatic Balancing Valves ASV – how they work

- Right distribution of pressure between branches
- Minimize mutual influence from branches
- Improve authority but not totally if the quantity of controlled terminal units is high.







For Optimum HVAC system performance and energy efficiency/ savings we need the below:

-The chilled water system to be hydronically balanced at full load (DRV or manual balancing) at partial load (DPCV).

-Improving control value characteristic with optimum authority for high efficiency exchange between water & air thus bringing delta T to the design value this will only be achieved by eliminating system pressure fluctuation effect on the control value throttle / stem.

In order to have all above features combined in one valve we need a **PRESSURE INDEPENDENT BALANCING & CONTROL VALVE**.



EmiratesGBC

Water Flow Direction



EmiratesGBC

What is the AB-QM?



- The AB-QM is a **P**ressure Independent **B**alancing and **C**ontrol **V**alve (PIBCV):
- Control valve
- Automatic balancing function





How does the AB-QM work

• The top part of the AB-QM is a control valve



How does the AB-QM work



• The bottom part of the AB-QM is a differential pressure controller that keeps a constant differential pressure across the control valve independent of pressure fluctuations in the system



How does the AB-QM work



- The pressure controller keeps a constant differential pressure across the control valve
- $Q = Kv \times \sqrt{\Delta P}$
- Constant differential pressure means:
 - Constant flow
 - Full authority











The AB-QM can be combined with a large range of actuators



- Self calibration to the stroke of the AB-QM
- Lin/Log/alpha setting to make the same valve/actuator combination linear or logarithmic
- High rangeability (256 steps at any preset)

Ρ

• Instant response to change in control signal





0V 10V

calibration Lin/Log/alpha



0V 0.5V

high rangeability



instant response



Applications

• AHU, Heating/Cooling





Applications

• Fancoil unit, Heating/Cooling





Applications



• Heat Exchangers



Less calculations

Selection of the AB-QM is based purely on

the flow:

- No KV calculations
- No need to calculate authority





Less Mounting/Installation

Mounting cost

- Installation time DN15 valve approx. 70 minutes
- Installation time DN40 approx. 80 minutes
- Installation time DN80 approx. 120 minutes
- Less commissioning time (normally at least 30 min./valve)
- No delay of handover
- Phased handovers





How does the AB-QM save energy



- Potential savings
 - pumping
 - ΔT to chiller
 - Temperature setting





Energy savings on pumping



DN20 valves with a flow of 500 l/h. 1 kW = 0,1 Euro

Energy saving on chiller

- A chiller is designed for 100% load but operates mostly (in case of traditional control valve) at 40% due low ΔT syndrome. Consequently additional chillers will be started by the control system to achieve requested cooling.
- AB-QM will increase chiller performance significantly, as we avoided overflow and thus are we able to increase ΔT





Energy saving on Chiller

- Higher (designed) return allows chiller to run more efficeint
- Variable primary hydronics
 - allow to run chillers in so called maxCap
 - more demanding to control valves
- To ensure maximum efficiency make sure to maximize ΔT







Increasing ΔT leads to higher energy efficiency

- Higher return temperature (with 3 K) for chillers (cooling system) results >10% energy saving
- Lower return temperature (< 60°C) for condensing boilers (heating system) results in ~10% energy saving





Energy saving on the temperature setting

- What constitutes a comfortable temperature is individual and varies through the day
- Imprecise control increases the chance of discomfort
- Discomfort causes complaints and increased use of energy
- By stabilizing the control the temperature can be optimised
- increasing the setting with 1K saves 10 to 16% of energy (Cooling)





Energy saving summary

- By reducing overflows the pump can run on a lower speed
- By improving the DT of the installation the efficiency of the chiller can be improved
- By increasing the performance of the control the temperature setting can be optimised





Danfoss NovoCon[®] smart actuator concept The best way to cut back on installation costs



Next step

Based on extensive customer feedback:

- More efficient builidng process
- More automation (data)
- Higher demands
 - Comfort
 - Energy efficiency

The result:

Smart actuator NovoCon®





4 system components combined in 1

Actuator

NovoCon[®] is a highly accurate multi-functional actuator



NovoCon[®] enables more than flow control via Fieldbus





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Flexibility in connections





Flexibility in connections:

- BACnet[™]/Modbus datacommunication
- 24 V connection
- Daisy chaining
- Analog signal input / output
- Temperature sensor wired or direct sensor





Remote setting design flow







Remote setting design flow





Remote features

- Flushing program
- De-air program





Remote feature: Flushing program







Remote feature: De-air program

BMS





Remote status feedback

- Error: No signal
- Error: Calibration
- Warning high temperature electronics
- Warning abnormal supply voltage
- Closing error due to obstruction
- No 0-10V control signal





Energy Management Min. Delta T Management

Description:

Smart actuator overrides the DDC control signal and maintains a minimum temperature difference between the flow and return temperatures by closing the valve when the user defined minimum is not achieved. When the flow temperature increases/decreases, so will the calculated minimum setpoint for the return temperature. This always ensures a minimum energy transfer to the FCU irrespective of the flow temperature.







Description:

- Actuator being primarily controlled by a DDC bus control signal in % valve opening.
- Actuator <u>will</u> override the DDC control signal when the user defined delta T is not achieved and the valve will begin to close.
- Actuator <u>is</u> gathering energy information about the FCU via 2 PT1000 pipe sensors.

Note:

- BV:22 will be activated if the sensors are missing or not connected properly.
- BV:23 will be activated to alert the user the user that this override function is active.
- BV:24 will be activated to alert the user if the user defined min. ΔT is out of the achieveable range.
- ΔT & temperature sensing units may be changed to °F via MSV:23.
- Logged Energy kWh may be changed to MJ or kBTU via MSV:27.



Energy Management Set Delta T Control

Description:

The smart actuator overrides the DDC control signal and maintains a constant temperature difference between the flow and return temperatures by opening and closing the valve when the user defined ΔT is exceeded or not achieved. When the flow temperature increases/decreases, so will the calculated ΔT setpoint for the return temperature. This always ensures a constant ΔT accross the FCU irrespective of the flow temperature.







Description:

- Actuator is primarily controlling itself and overwriting DDC bus control signal in % valve opening.
- Actuator will open and close accordingly in maintaining the user defined set ΔT value.
- Actuator is gathering energy information about the FCU via 2 PT1000 pipe sensors.

Note:

- BV:22 will be activated if the sensors are missing or not connected properly.
- BV:23 will be activated to alert the user the user that this override function is active.
- BV:24 will be activated to alert the user if the user defined set ΔT is out of the achieveable range.
- ΔT & temperature sensing units may be changed to °F via MSV:23.
- Logged Energy kWh may be changed to MJ or kBTU via MSV:27.



Remote alpha setting for optimal control

- Optimal control is possible, if we have linear response of system. Characteristic of HEX can be compensated with characteristic of actuator by appropriate α value.
- On NovoCon you can set the value remotely using BACnet command.
- α =0.2 (logarithmic), α =1 (linear).





LED bar on NovoConTM

Network status BACnet(RS485) activity

Valve position Indication of valve position Movement LED's show if Novocon[™] is opening or closing

Errors

Abnormal voltage supply, internal temperature, obstruction during closing



Local control options



Manual override Open or close valve by hand Reset button Recalibration or restore factory settings

DIP switch Manual MAC addressing and setting for termination resistor



Flow indication

How is it possible ?

Precision stepper motor for precise spindle position Maintaining constant differential pressure







Daisy-chaining Select and adapt the Smart actuator

- Additional voltage booster each 7 – 11 NovoCon's.
- Chain max. 64 pcs







Sticker on the smart actuator



Conclusions



Dankiss.

- Faster, remote commissioning
- Energy optimisation
- Faster problem location
- Faster remote maintenance



1 click

to flush hundreds of AB-QM valves

Time is the biggest saving

Alarms and status are feedback to the Building Automation System via Fieldbus

Remote system verification:

 \checkmark wiring to actuator

 \checkmark connection to valve

✓ valve pre-setting

 \checkmark valve operation

No need to visit site





Thank You